

- GRADED HW 3 AND HW 4 AVAILABLE, SOLUTIONS POSTED ON WEB
- HW 5 GRADED (+ SOLUTIONS) BY EOD MONDAY
- MIDTERM REVIEW SESSION MONDAY 5-6 PM
- MIDTERM REVIEW INFO SHEET AVAILABLE ON WEB SITE BY EOD FRIDAY
- ADVANCED LECTURE NEXT WEEK, MONDAY 4-5 PM
- MIDTERM IN TESTING CENTER NEXT WEEK, TUESDAY-FRIDAY  
(3 HOUR, CLOSED NOTES, CLOSED BOOK, MIXED MULTIPLE CHOICE AND HOMEWORK-TYPE PROBLEMS)

## PARALLEL-RAY RECONSTRUCTION IN CT

RECALL THAT FOR MULTI-ENERGETIC BEAMS, THE INTENSITY  $I_d$  AT A GIVEN DETECTOR IS GIVEN BY:

$$I_d = \int_0^{E_{\max}} \underbrace{E S(E)}_{\text{X-RAY SPECTRUM}} e^{-\int_0^{r(x,y)} \mu(s,E) ds} dE \quad \leftarrow \begin{array}{l} \text{LOCATION OF DETECTOR} \\ \text{BASIC X-RAY} \\ \text{IMAGING} \\ \text{EQUATION} \end{array}$$

DEALING WITH THE INTEGRAL OVER  $E$  IS A PAIN. WE TYPICALLY JUST DEAL WITH AN EFFECTIVE ENERGY  $\bar{E}$ . WE THEN HAVE:

$$I_d = I_0 e^{-\int_0^{r(x,y)} \mu(s) ds}$$

INSTEAD OF DEALING WITH INTENSITIES, WE DEFINE THE BASIC MEASUREMENT OF A CT SCANNER AS:

$$g_D \equiv -\ln\left(\frac{I_d}{I_0}\right) = \int_0^{r(x,y)} \mu(s) ds$$

THUS, THE BASIC MEASUREMENT OF A CT SCANNER IS JUST A LINE INTEGRAL OF THE LINEAR ATTENUATION COEFFICIENT AT THE EFFECTIVE ENERGY OF THE SCANNER.

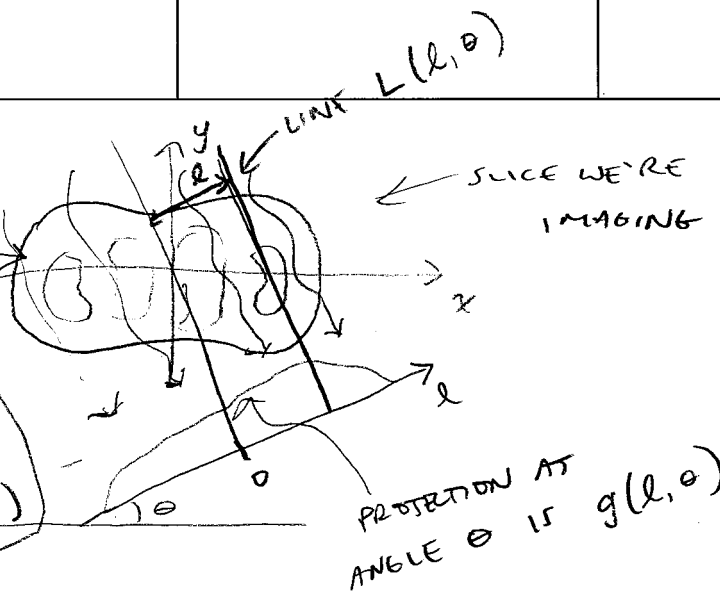
FROM THIS WE RECONSTRUCT CT NUMBER AT EACH PIXEL.

$$h = 1000 \times \frac{\mu - \mu_{H_2O}}{\mu_{H_2O}}$$

IN HOUNSFIELD  
UNITS

NOW LET'S PUT SOME MATH BEHIND OUR PROJECTIONS.

$f(x,y)$   
GIVES  
u AT  
EACH  
LOCATION  
(i.e., WHAT  
WE WANT  
TO RECONSTRUCT)



AT A GIVEN ANGLE  $\theta$ ,  $g(l, \theta)$  IS GIVEN BY:

$$g(l, \theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x,y) \delta(x \cos \theta + y \sin \theta - l) dx dy$$

- $g(l, \theta)$  AT A GIVEN  $\theta$  IS A PROJECTION.
- $g(l, \theta)$  FOR ALL  $l$  AND  $\theta$  IS THE 2-D RADON TRANSFORM OF  $f(x,y)$ .
- A PLOT OF  $g(l, \theta)$  WITH  $\theta$  ALONG THE VERTICAL AXIS AND  $l$  ALONG THE HORIZONTAL AXIS IS CALLED A SINOGRAM

EXAMPLE: (6.2 IN BOOK)

LET:  $f(x,y) = \begin{cases} 1 & , x^2 + y^2 \leq 1 \\ 0 & , \text{else} \end{cases}$

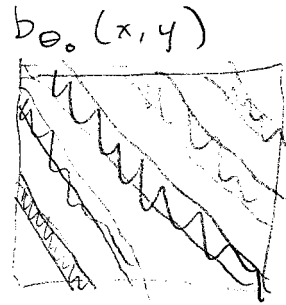
- WHAT IS 2-D RADON TRANSFORM?
- WHAT IS THE SINOGRAM?
- WHAT CHARACTERISTICS WILL THE SINOGRAM HAVE OF A CIRCULARLY SYMMETRIC FUNCTION?

BACK PROJECTION:

SUPPOSE WE KNOW  $g(l, \theta_0)$  FOR SOME  $\theta_0$ . THERE ARE AN INFINITE # OF  $f(x, y)$  THAT COULD GIVE THIS SINGLE PROJECTION. WE TAKE AN INTUITIVE GUESS AT WHAT  $f(x, y)$  MIGHT LOOK LIKE (IGNORING SCALING) BY "SMEARING" THE PROJECTION IN THE PROJECTION DIRECTION TO FORM AN IMAGE:

$$b_{\theta_0}(x, y) = g(x \cos \theta_0 + y \sin \theta_0, \theta_0) \leftarrow \text{BACK PROJECTION AT ANGLE } \theta_0 \text{ FOR } g(l, \theta_0)$$

$$x \cos \theta_0 + y \sin \theta_0 = l$$



- IF WE SUM  $b_{\theta}(x, y)$  AT A BUNCH OF DIFFERENT  $\theta$ , WE START TO GET AN APPROXIMATION TO THE IMAGE.
- IN THE CONTINUOUS CASE, WE HAVE:

$$f_b(x, y) = \int_0^{\pi} b_{\theta}(x, y) d\theta \leftarrow \begin{matrix} \text{"LAMINOGRAM"} \\ \text{OR} \\ \text{"BACK PROJECTION SUMMATION IMAGE"} \end{matrix}$$

- THIS IS WHAT EARLY SCANNERS DID, BUT IT IS ONLY AN APPROXIMATION. (IN OTHER WORDS, IT IS WRONG.)

PROJECTION-SLICE THEOREM:

CONSIDER A PROJECTION  $g(l, \theta_0)$  OF OUR OBJECT  $f(x, y)$ .

IF  $G(k_e, \theta_0)$  IS THE 1-D FOURIER TRANSFORM (WITH RESPECT TO  $l$ ) OF  $g(l, \theta_0)$ , THEN:

$$\boxed{G(k_e, \theta_0) = F(k_e \cos \theta_0, k_e \sin \theta_0)} \quad \begin{matrix} \text{"PROJECTION-SLICE} \\ \text{THEOREM"} \\ \text{OR "CENTRAL SECTION} \\ \text{THEOREM"} \end{matrix}$$

WHERE  $F(k_x, k_y)$  IS THE 2D FOURIER TRANSFORM OF  $f(x, y)$ .

PROOF:

$$G(k_e, \theta_0) = \int_{-\infty}^{\infty} g(l, \theta) e^{-j2\pi k_e l} dl \quad \leftarrow \text{DEFINITION OF 1D F.T.}$$

$$= \int_{-\infty}^{\infty} \underbrace{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \delta(x \cos \theta_0 + y \sin \theta_0 - l) dx dy}_{g(l, \theta_0)} e^{-j2\pi k_e l} dl$$

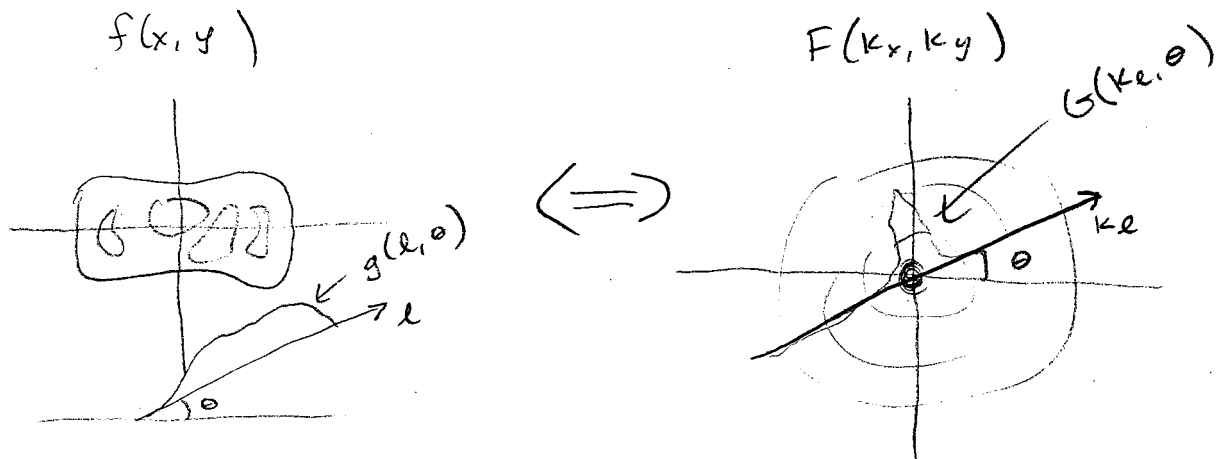
$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \int_{-\infty}^{\infty} e^{-j2\pi k_e l} \delta(x \cos \theta_0 + y \sin \theta_0 - l) dl dx dy$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi k_e (x \cos \theta_0 + y \sin \theta_0)} dx dy \quad \leftarrow \begin{matrix} \text{SIFTING} \\ \text{PROPERTY} \\ \text{OF DATA} \end{matrix}$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi (k_e \cos \theta_0 x + k_e \sin \theta_0 y)} dx dy$$

$$= F(k_e \cos \theta_0, k_e \sin \theta_0) \quad \checkmark$$

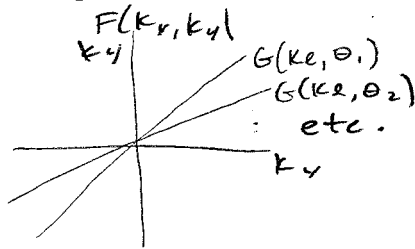
GRAPHICALLY THIS MEANS:



- THE PROJECTION-SLICE THEOREM FORMS THE BASIS FOR MODERN CT RECONSTRUCTION TECHNIQUES.
- ALSO HAS APPLICATIONS IN MRI!

THE FOURIER METHOD OF CT RECONSTRUCTION:

- MEASURE PROJECTIONS  $g(l, \theta)$  AT A BUNCH OF  $\theta$ .
- 1-D FOURIER TRANSFORM TO GET  $G(k_l, \theta)$ .
- INTERPOLATE ONTO A CARTESIAN GRID TO GET  $F(k_x, k_y)$



- WE NOW HAVE  $F(k_x, k_y)$  AND CAN DO AN INVERSE 2DFT TO GET  $f(x, y)$ !

- THIS IS VERY ACCURATE, BUT COMPUTATIONALLY INTENSIVE.
- CAN WE USE PROJECTION-SLICE THEOREM TO IMPROVE BACK PROJECTION? YES!  $\Rightarrow$  FILTERED BACK PROJECTION

### FILTERED BACK PROJECTION:

RECALL THAT:

$$f(x,y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(k_x, k_y) e^{j2\pi(xk_x + yk_y)} dk_x dk_y$$

← JUST DEFINITION OF 2DFT INVERSE

WE CAN WRITE THIS IN POLAR COORDINATES AS:

$$f(x,y) = \int_0^{2\pi} \int_0^{\infty} F(k_e \cos \theta, k_e \sin \theta) e^{j2\pi(k_e \cos \theta x + k_e \sin \theta y)} k_e dk_e d\theta$$

SINCE:  $k_x = k_e \cos \theta$   
 $k_y = k_e \sin \theta$

FROM THE PROJECTION-SLICE THEOREM, WE KNOW:

$$F(k_e \cos \theta, k_e \sin \theta) = G(k_e, \theta)$$

SO:

$$f(x,y) = \int_0^{2\pi} \int_0^{\infty} G(k_e, \theta) e^{j2\pi k_e (x \cos \theta + y \sin \theta)} k_e dk_e d\theta$$

USING:  $g(r, \theta) = g(-r, \theta + \pi)$ , YOU FIND:

$$f(x,y) = \int_0^{\pi} \int_{-\infty}^{\infty} |k_e| G(k_e, \theta) e^{j2\pi k_e (x \cos \theta + y \sin \theta)} dk_e d\theta$$

OR:

$$f(x,y) = \int_0^{\pi} \left[ \int_{-\infty}^x |k_e| G(k_e, \theta) e^{j2\pi k_e l} dk_e \right]_{l=x \cos \theta + y \sin \theta} d\theta$$

THIS IS A FILTERED VERSION OF  $g(r, \theta)$ !  
 (MULTIPLICATION IN FOURIER SPACE)

SO IN FILTERED BACK PROJECTION, WE FILTER EACH  $g(r, \theta)$  [BY TAKING 1-D F.T. AND MULTIPLYING BY FILTER TRANSFER FUNCTION  $|k_e|$ , AND THEN DOING INVERSE 1-D F.T.] AND THEN BACKPROJECT!

INTUITIONS:

- COMPENSATION FOR SAMPLING DENSITY

CONVOLUTION BACKPROTECTION:

- SAME THING AS FILTERED BACKPROTECTION, EXCEPT FILTERING OF  $g(r, \theta)$  IS DONE BY CONVOLUTION IN THE SPATIAL DOMAIN W/  $\mathcal{F}^{-1} [ |k_x| ]$

$\uparrow$   
"RAMP FILTER"

FAN-BEAM GEOMETRY:

- WE WON'T GO INTO TOO MUCH DETAIL. IN BOOK
- COMMON VARIATION FOR FAN-BEAM GEOMETRY IS CONVOLUTION WEIGHTED - BACKPROTECTION

- FILTERED PROJECTIONS ARE BACKPROTECTED ALONG THE X-RAY PATHS OF INTEGRATION.
- WEIGHTING IS APPLIED THAT DEPENDS ON DISTANCE FROM SOURCE.

A FEW WORDS ON SAMPLING IN CT:

- IN OUR DISCUSSIONS, WE HAVE ASSUMED CONTINUOUS DATA IN BOTH  $\theta$  AND  $\rho$ .
- IN PRACTICE, WE HAVE A LIMITED NUMBER OF PROJECTIONS (DIFFERENT VALUES OF  $\theta$ ) AND DETECTOR SAMPLES (DIFFERENT VALUES OF  $\rho$ ) CALLED  
"VIEWS"
- HOW MANY VIEWS & DETECTOR SAMPLES ARE NEEDED?  
(EXIST TO DERIVE FOR 16 GEOMETRIES)

WE WILL DISCUSS THIS IN THE ADVANCED LECTURE  
MONDAY.